

CORRECTION PIPELINE EVOLUTION

Marc OLLIVIER, Sylviane CHAINTREUIL, Adrien
FERRIGNO, Alexis DERU

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INSTRUMENTAL CORRECTION PHILOSOPHY



- N0 generated at CNES
- 2 successive correction pipeline
 - ◆ N0 -> N1 : On the fly corrections (board and ground) on N0 data : generation of N1 data
 - ◆ N1 -> N2 : a posteriori correction (after the run end) requiring parameters computed over a whole run
- Correction of the effect only if it is identified / modelled / quantified
- Neither blind corrections, nor systematic removal (using SYSREM or another algorithm).

PIPELINE N0 -> N1



- **Seismo field (corrections applied successively)**
 - ◆ 1. EMI removal : using a pattern obtained during the calibration phase
 - ◆ 2. Removal of offset and background residuals (on board background subtraction)
 - ◆ 3. Correction of the observation duration and absolute date
 - ◆ 4. Correction of the jitter using high resolution PSFs
- **Exo field (corrections applied successively)**
 - ◆ 1. EMI removal : using a pattern obtained during the calibration phase
 - ◆ 2 removal of offset and a median background pattern (obtained using background windows) : spatially uniform correction
 - ◆ 3 on chromatic LC: generation of the white light LC
 - ◆ 4. Correction of the observation duration and absolute date
 - ◆ 5. Correction of the jitter using medium resolution PSFs
- **Seismo and Exo fields (corrections applied successively after specific corrections)**
 - ◆ 1. Correction of the relativistic aberration
 - ◆ 2. Flag of the outliers (flag for points at a level $> 5\sigma$ of a sliding mean)
 - ◆ 3. Identification of orbital events (SAA, in/out of eclipses...)

PIPELINE N1 -> N2



● Exo and Seismo data

- ◆ translation of UT datations into heliocentric time
- ◆ Correction of thermal jumps within the camera
- ◆ Correction of the detection chain efficiency loss

● Seismo field

- ◆ re-sampling 1s -> 32 s : satellite time (« raw » data)
- ◆ Correction of T and mask changing jumps (« hel » et « helreg »)
- ◆ translation satellite time into heliocentrique time (« hel » data)
- ◆ re-samplct at 32 s sharp in heliocentric time (« helreg » data)
- ◆ search for / correction of proton impacts (« hel » and « helreg » data)

● Exo field

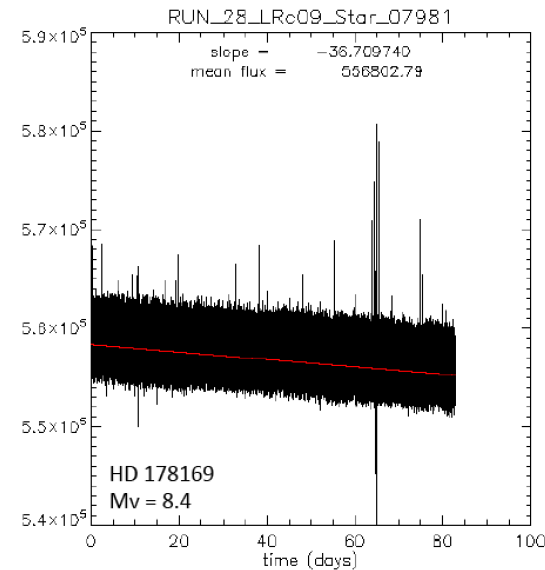
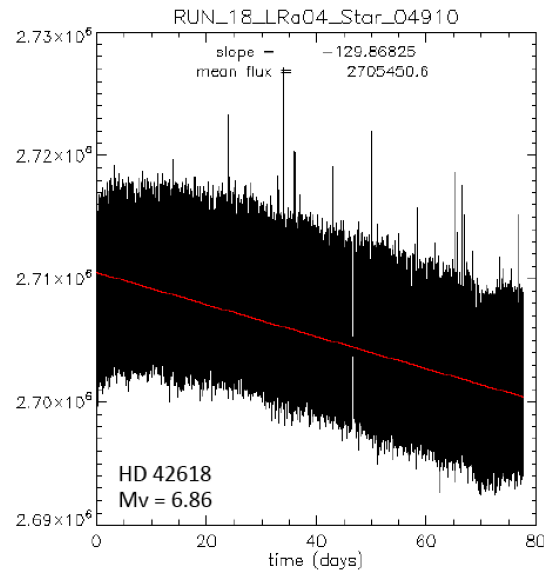
- ◆ 1merging of data at a sampling rate of 512 and 32 s into a unique LC
- ◆ 2. Flag of hot pixels
- ◆ 3. Generation of the « windescriptor » containing the observation information for each target.

AGEING OF THE INSTRUMENT



- Decrease of the detection chain efficiency

- ◆ Decrease of the optical transmission
- ◆ Decrease of the quantum efficiency



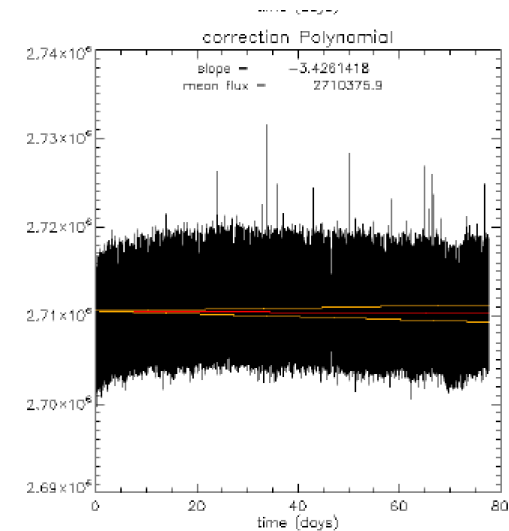
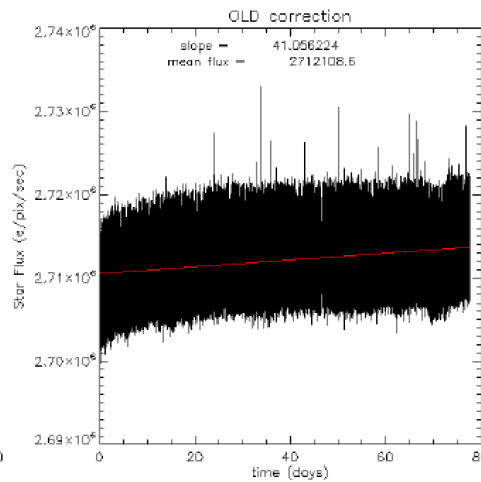
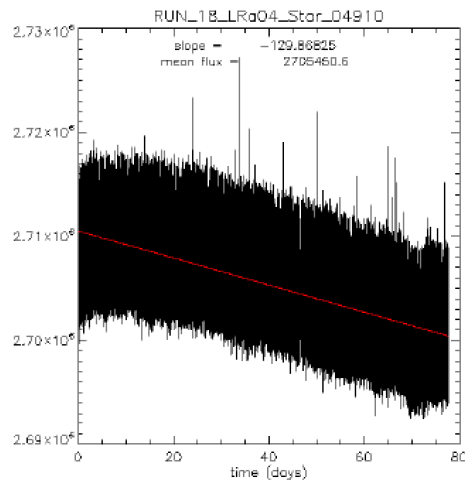
- ◆ Effect estimated thanks to the observation of stable stars (variation over 1 run) and re-observation of several targets (long term variation) : efficiency loss of about 10% over 6 years.

AGEING OF THE INSTRUMENT



● Decrease of the detection chain efficiency

- ◆ over correction of several LC with classical correction
- ◆ New estimation of the correction amplitude as a function of the stellar flux of reference (stable) (A. Deru : LESIA)
- ◆ Correction for both seismo and exo LC
- ◆ Correction accuracy : 10 %



HD 42618
Mv = 6.86

Error of correction : 9.9799653 %
Slope max : 9.1926716
Slope min : -16.044957

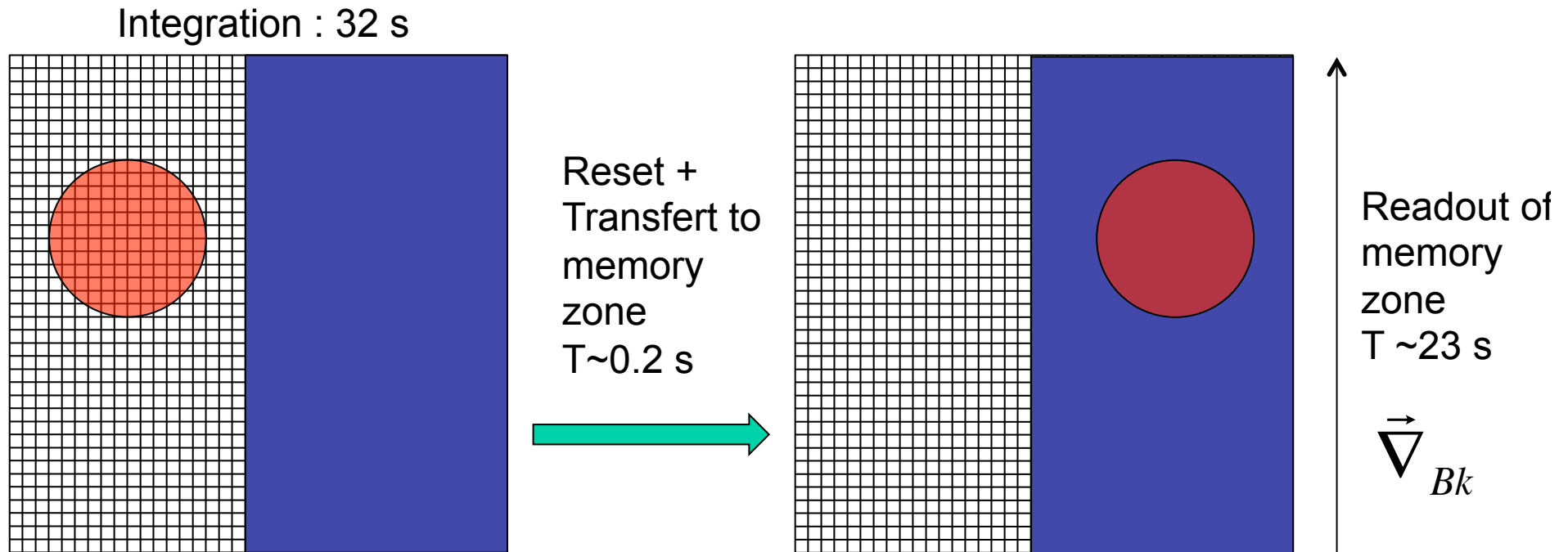
AGEING OF THE INSTRUMENT



- Increase of the detector dark current

- Negligible/neglected at the beginning of CoRoT
- Increases with time (and irradiation)

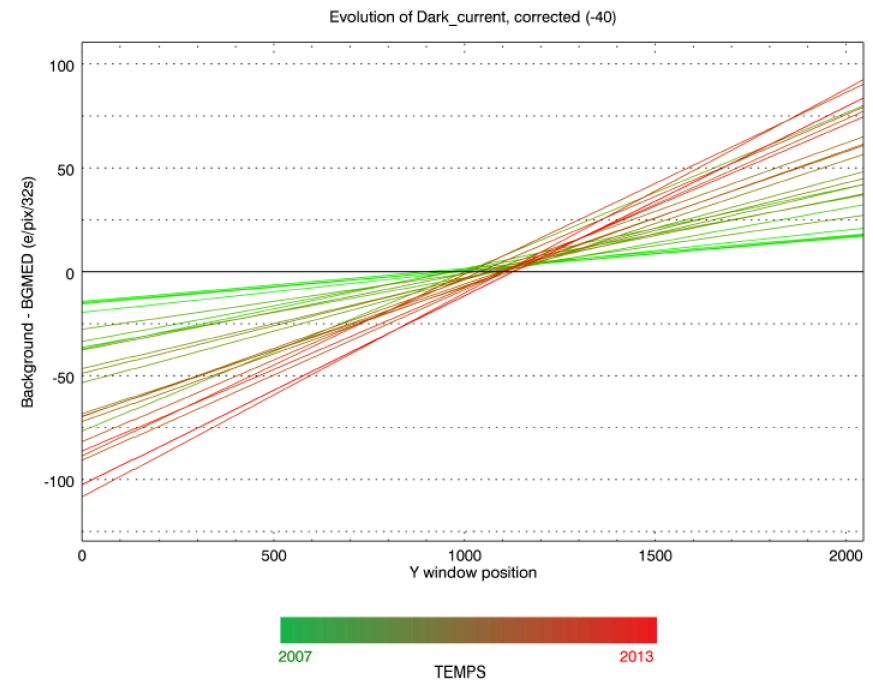
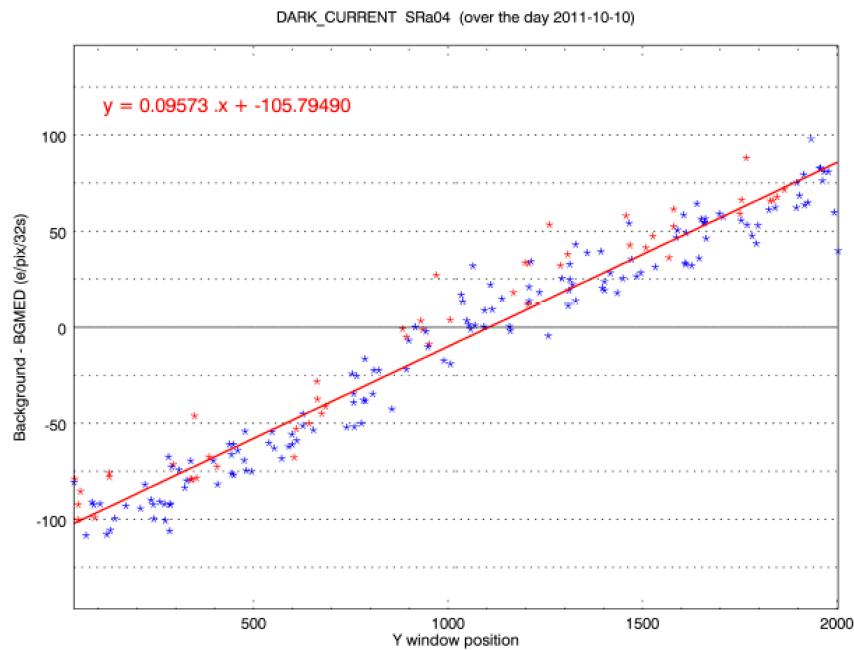
➔ Background residual on ExO LC, depending on the target position on the CCD.



AGEING OF THE INSTRUMENT



- Evolution of the dark current with time



AGEING OF THE INSTRUMENT



● Correction of the Exo background

- Model of the background

$$BG(t) = C_T \times [32 + \tau(y)] + sky_{BG} + scatlight(t)$$

BG = total background on the CCD

C_T = Coefficient (function of run, T)

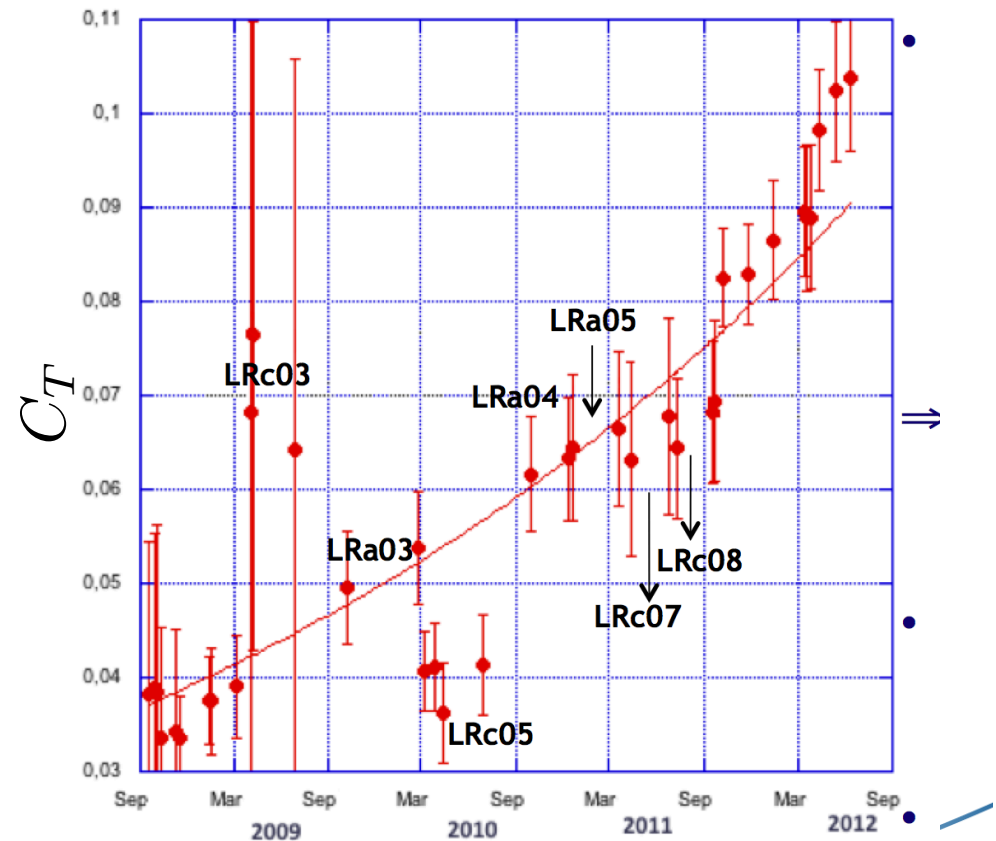
$\tau(y)$ = CCD readout time

sky_{BG} = sky contribution

Scatlight(t) = scattered light

● status

- Pipeline ready
- Production should start

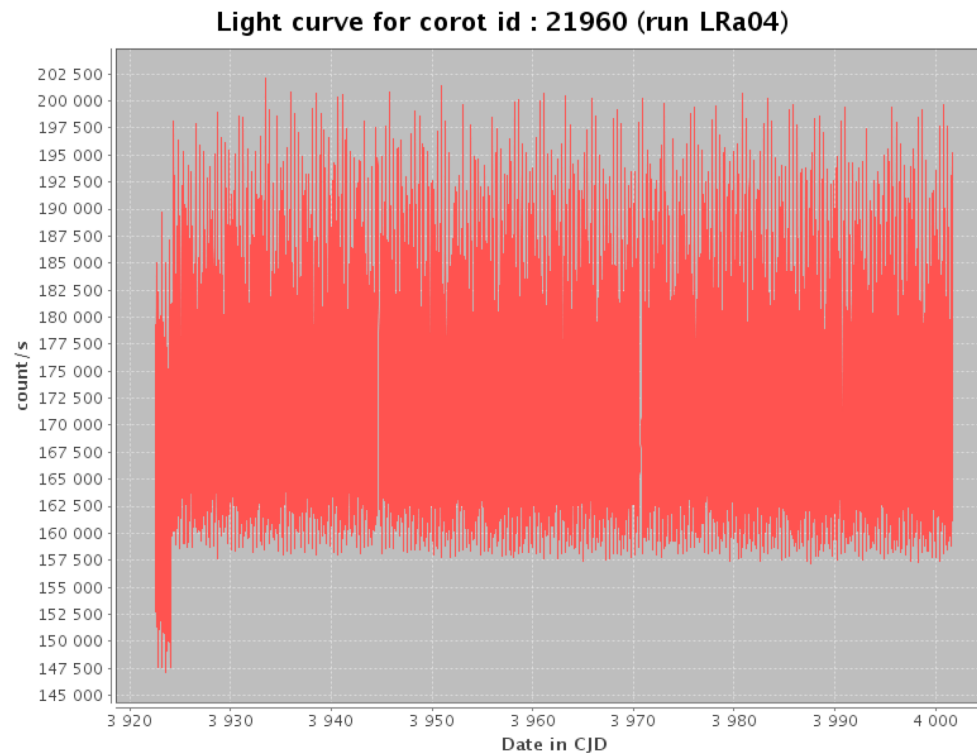


OTHER CORRECTIONS



● Photometric jumps on seismo data

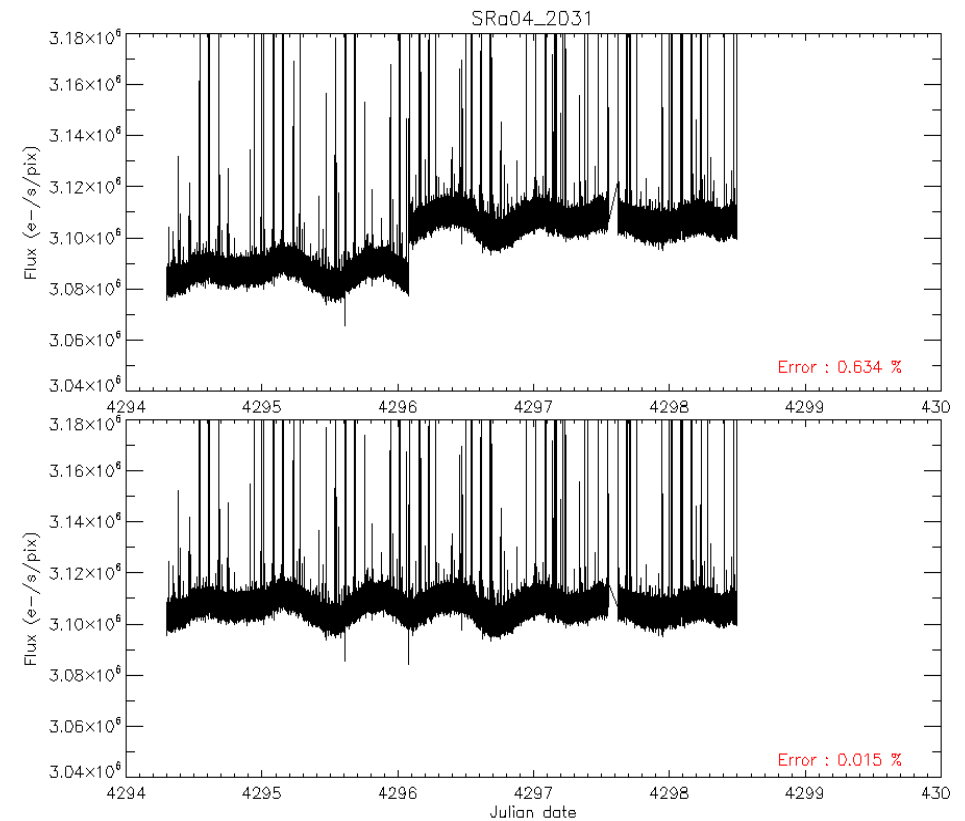
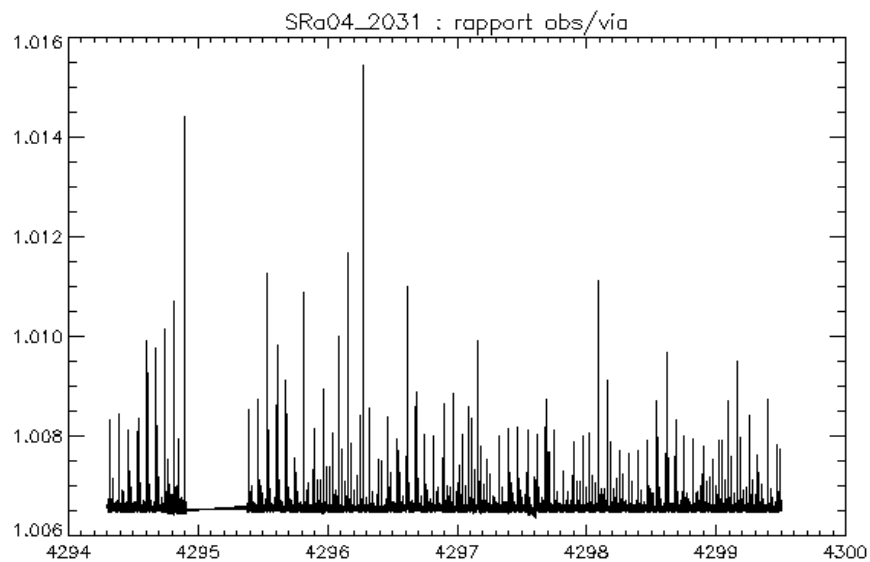
- Due to the change rough -> fine mask
- Correction using seismo imagerettes to compute the photometric loss



OTHER CORRECTIONS



- Photometric jumps on seismo data
 - works well (except for 8 stars)

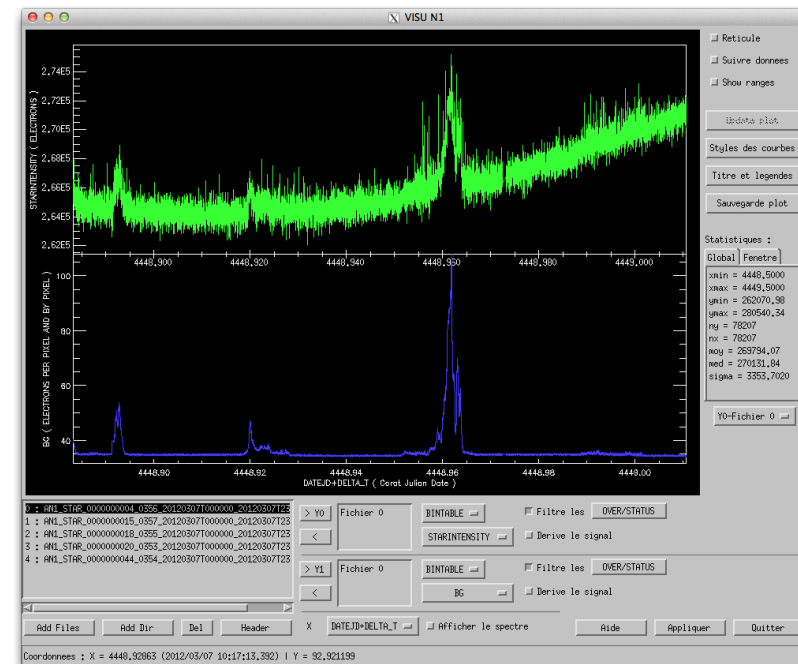
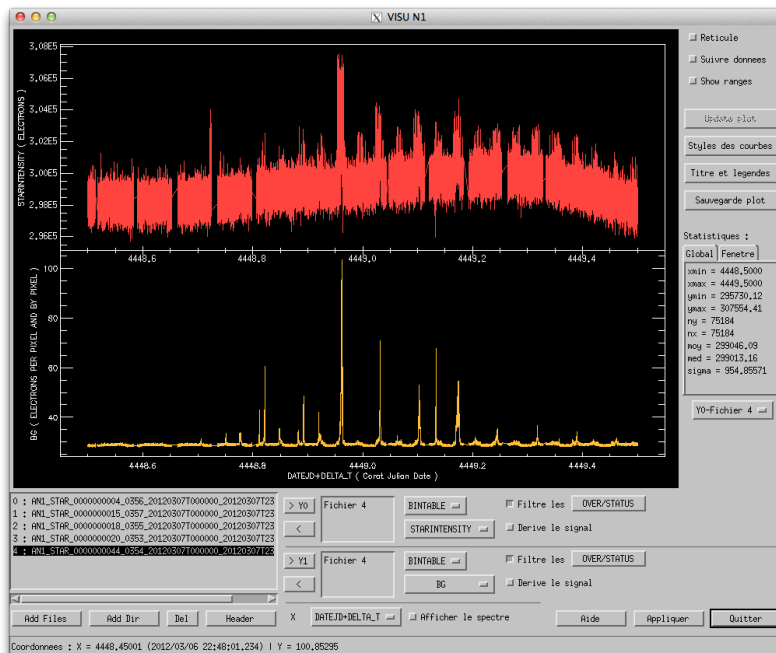


OTHER CORRECTIONS



Background residuals on seismo and exo LC

- Out of SAA residuals :
- Duration : several minutes
- Happens during several hours at about the orbital frequency every 21 to 24 days
- Can be seen on every Seismo window
- Not evident on Exo windows
- No evident correlation with orbital events



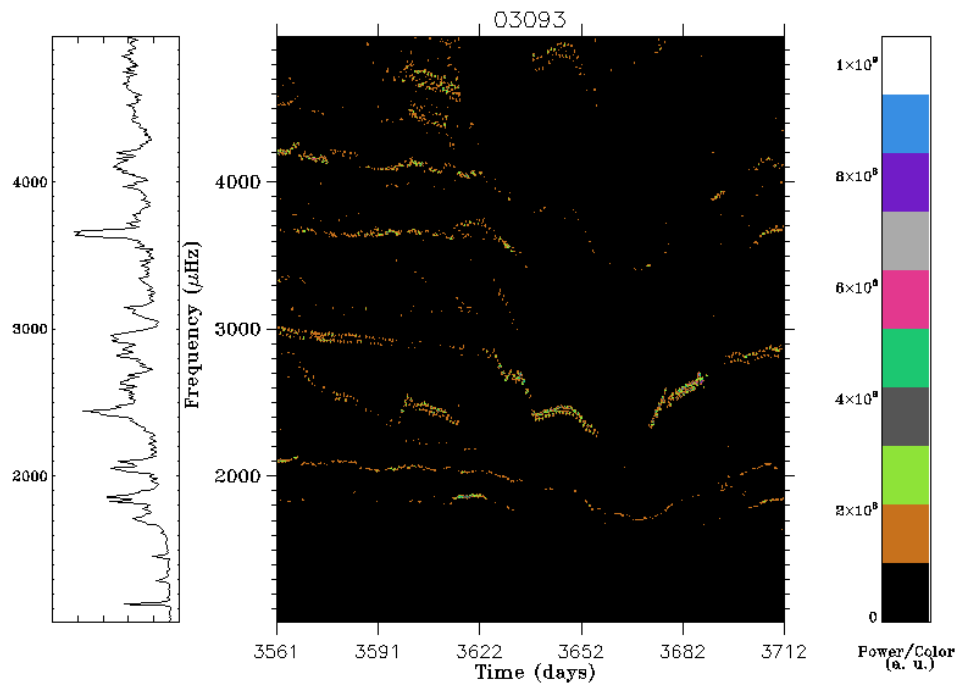
OTHER EFFECTS



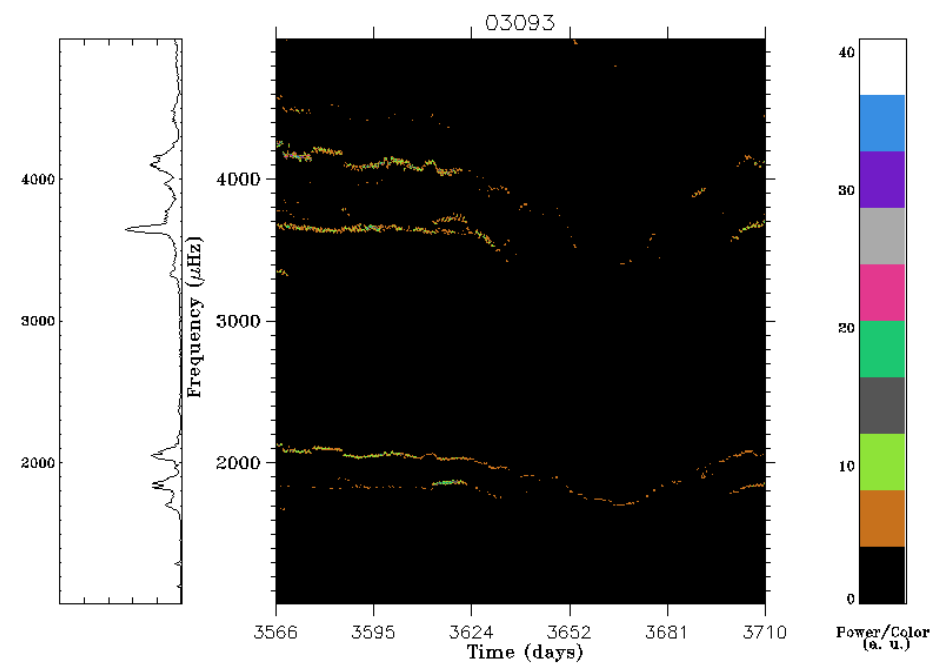
● Effects to be considered

- Photometric jumps in the Exo LC : hot pixels
- Noise frequencies in the seismo LC: jitter residuals

Photometry



Jitter residuals



DISCUSSION AT THE CEST



● 2 major effects identified on exo LC that may be corrected

- Jumps in the LC : specific for each LC (each color)
- Correlated residuals at the orbital period and others : global detrending

● Proposed improvement

- No new level
- Within the N2 data, 1 or 2 new levels of correction (as for the N2 seismo)
- Correction of jumps
- Detrended LC (using a sysrem algorithm)
- -> a new level of data for people outside the present CoRoT community : EasyCoRoT

● How to ?

- Difficult to organise a dedicated workshop before december
- Make a list of existing things (on personal laptops)
- Identify the right persons
- Select the right algorithms and transform them into robust routines included in the production pipeline